Finsler and Cartan geometric physical backgrounds arXiv:1403.4005 [math-ph]

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Moduli Operads Dynamics II Tallinn – 4 June 2014

Outline

- Introduction
- Causality
- 3 Observers
- Gravity
- Conclusion

- Metric geometry of spacetime serves multiple roles:
 - Causality
 - Observers, observables and observations
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 - How to serve the same roles as metric geometry?

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- Possible explanations of yet unexplained phenomena:
 - Fly-by anomaly
 - Galaxy rotation curves
 - Accelerating expansion of the universe

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- Solution:
 - Consider space O of all allowed observers.
 - Describe experiments on observer space instead of spacetime.
 - ⇒ Observer dependence of physical quantities follows naturally.
 - ⇒ No preferred observers.
 - Geometry of observer space modeled by Cartan geometry.

Geometrical structures

Metric geometry

Manifold *M*Lorentzian metric *g*Orientation

Time orientation

Finsler geometry

Tangent bundle *TM*Geometry function

 $L: TM \to \mathbb{R}$

Finsler function

 $F:TM \to \mathbb{R}$

Finsler metric $g^F(x, y)$

Cartan non-linear connection N^a_b

Cartan linear connection ∇

Cartan geometry

Lie group $G = ISO_0(3, 1)$

Closed subgroup

K = SO(3)

Principal K-bundle

 $\pi: P \to O$

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From metric to Finsler

Coordinates (x^a) on MCoordinates (x^a, y^a) on TMDefine $L(x, y) = g_{ab}(x)y^ay^b$

From Finsler to Cartan

Space O of observer 4-velocities Space P of observer frames Define A from connection ∇

Metric spacetime geometry

- Ingredients of metric spacetime geometry:
 - 4-dimensional spacetime manifold M.
 - Metric g_{ab} of Lorentzian signature (-,+,+,+).
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- \Rightarrow Arc length for curves $t \mapsto \gamma(t) \in M$ defined by the metric:

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- Observables are components of tensor fields.
- Tensor components must be expressed in suitable basis.
- ⇒ Metric provides notion of orthonormal frames:

$$g_{ab}f_i^af_j^b=\eta_{ij}$$
.

Basics of Finsler spacetimes

• Finsler geometry defined by length functional for curve γ :

$$au_2 - au_1 = \int_{t_1}^{t_2} F(\gamma(t), \dot{\gamma}(t)) dt$$

- Finsler function $F: TM \to \mathbb{R}^+$.
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- Introduce manifold-induced coordinates (x^a, y^a) on TM:
 - Coordinates x^a on M.
 - Define coordinates y^a for $y^a \frac{\partial}{\partial x^a} \in T_x M$.
 - Tangent bundle *TTM* spanned by $\left\{\partial_a = \frac{\partial}{\partial x^a}, \bar{\partial}_a = \frac{\partial}{\partial y^a}\right\}$.

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 - Tangent bundle *TTM* spanned by $\left\{\partial_a = \frac{\partial}{\partial x^a}, \bar{\partial}_a = \frac{\partial}{\partial y^a}\right\}$.
- *n*-homogeneous functions on *TM*: $f(x, \lambda y) = \lambda^n f(x, y)$.
 - *n*-homogeneous smooth geometry function $L: TM \to \mathbb{R}$.
 - \Rightarrow 1-homogeneous Finsler function $F = |L|^{\frac{1}{n}}$.
- ⇒ Finsler metric with Lorentz signature:

$$g_{ab}^F(x,y) = \frac{1}{2}\bar{\partial}_a\bar{\partial}_b F^2(x,y).$$

Connections on Finsler spacetimes

• Cartan non-linear connection:

$$N^a{}_b = rac{1}{4} \bar{\partial}_b \left[g^F{}^{ac} (y^d \partial_d \bar{\partial}_c F^2 - \partial_c F^2) \right] \, .$$

⇒ Berwald basis of *TTM*:

$$\{\delta_a = \partial_a - N^b{}_a \bar{\partial}_b, \bar{\partial}_a\}$$
.

 \Rightarrow Dual Berwald basis of T^*TM :

$$\{dx^a, \delta y^a = dy^a + N^a{}_b dx^b\}.$$

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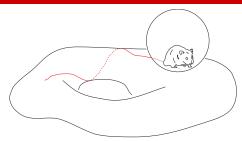
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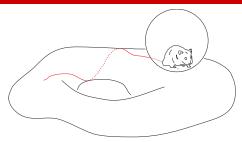
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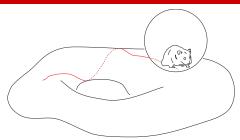
- \Rightarrow Splits $TTM = HTM \oplus VTM$ and $T^*TM = H^*TM \oplus V^*TM$.
- Cartan linear connection:



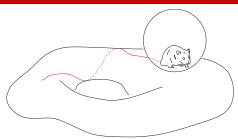
- Consider a hamster ball on a two-dimensional surface:
 - Two-dimensional Riemannian manifold (M, g).
 - Orthonormal frame bundle $\pi: P \to M$ is principal SO(2)-bundle.
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 - "Rolling without slippling" over M: quotient space $\mathfrak{z} = \mathfrak{so}(3)/\mathfrak{so}(2)$.
- \Rightarrow Surface M "traced" by $S^2 \cong SO(3)/SO(2) = G/H$.
- \Rightarrow Geometry of *M* fully described by Hamster ball motion.

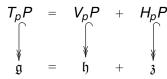
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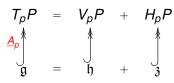
$$A_{p} = \omega_{p} + \theta_{p}$$

$$g = h + 3$$

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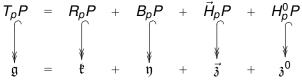
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- \Rightarrow Geometry of *M* encoded in *A* resp. \underline{A} .

Cartan geometry of observer space

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- Cartan connection $A = \Omega + b + \vec{e} + e^0 \in \Omega^1(P, \mathfrak{g})$.
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- \Rightarrow Geometry of M encoded in A resp. \underline{A} . [S. Gielen, D. Wise '12]

From metric to Finsler

Metric-induced 2-homogeneous geometry function:

$$L(x,y)=g_{ab}(x)y^ay^b.$$

- \Rightarrow Finsler function $F(x, y) = \sqrt{|L(x, y)|}$.
- ⇒ Finsler metric

$$g^F(x,y) = \begin{cases} -g(x,y) & \text{for } y \text{ timelike,} \\ g(x,y) & \text{for } y \text{ spacelike.} \end{cases}$$

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⇒ Cartan linear connection:

$$F^{a}_{bc} = \Gamma^{a}_{bc}, \quad C^{a}_{bc} = 0.$$

From Finsler to Cartan

- Need to construct $A \in \Omega^1(P, \mathfrak{g})$.
- Recall that

$$\mathfrak{g} = \mathfrak{h} \oplus \mathfrak{z}$$
 $A = \omega + e$

Definition of e: Use the solder form:

$$e^i = f^{-1}{}^i_a dx^a$$
.

• Definition of ω : Use the *Cartan linear connection*:

$$\omega^{i}_{j} = f^{-1}{}^{i}_{a} \left[df^{a}_{j} + f^{b}_{j} \left(dx^{c} F^{a}_{bc} + (dx^{d} N^{c}_{d} + df^{c}_{0}) C^{a}_{bc} \right) \right] .$$

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- Let $a = z^i \mathcal{Z}_i + \frac{1}{2} h^i{}_j \mathcal{H}_i{}^j \in \mathfrak{g}$.
- Fundamental vector fields:

$$\underline{A}(a) = z^{i} f_{i}^{a} \left(\partial_{a} - f_{j}^{b} F^{c}{}_{ab} \bar{\partial}_{c}^{j} \right) + \left(h^{i}{}_{j} f_{i}^{a} - h^{i}{}_{0} f_{i}^{b} f_{j}^{c} C^{a}{}_{bc} \right) \bar{\partial}_{a}^{j}.$$

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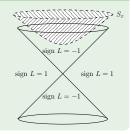
Causal structure

Metric geometry

Geometry function:

$$L = g_{ab} y^a y^b$$

 y^a timelike for L < 0.



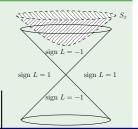
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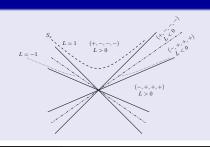


Finsler geometry

Fundamental geometry function *L* Hessian:

$$g_{ab}^L(x,y) = \frac{1}{2}\bar{\partial}_a\bar{\partial}_b L(x,y)$$

Use sign of L and signature of g^{L} .



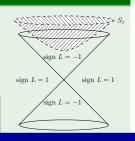
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Cartan geometry

Observer space:

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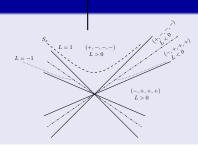
O contains only future unit timelike vectors.

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Use sign of L and signature of g^L .



Causality of Finsler spacetimes

"Unit timelike condition" required for Finsler spacetimes:
 For all x ∈ M the set

$$\Omega_{X} = \left\{ y \in T_{X}M \left| |L(x,y)| = 1, \operatorname{sig} \bar{\partial}_{a} \bar{\partial}_{b} L(x,y) = (\epsilon, -\epsilon, -\epsilon, -\epsilon) \right. \right\}$$

with $\epsilon = L(x, y)/|L(x, y)|$ contains a non-empty closed connected component $S_x \subseteq \Omega_x \subset T_x M$.

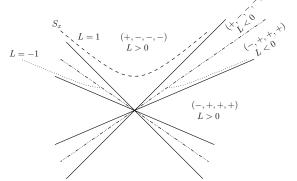
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with $\epsilon = L(x, y)/|L(x, y)|$ contains a non-empty closed connected component $S_x \subseteq \Omega_x \subset T_x M$.

- $\Rightarrow S_x$ contains physical observers.
- $\Rightarrow \mathbb{R}^+ S_x$ is convex cone.



The observer frame bundle

- Observer space of a Finsler spacetime:
 - Consider all allowed observer tangent vectors:

$$O=\bigcup_{x\in M}S_x.$$

• Tangent vectors $y \in S_x$ satisfy $g_{ab}^F(x, y)y^ay^b = 1$.

The observer frame bundle

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- Tangent vectors $y \in S_x$ satisfy $g_{ab}^F(x, y)y^ay^b = 1$.
- Construct orthonormal observer frames:
 - \Rightarrow Complete $y = f_0$ to a frame f_i with $g_{ab}^F(x,y)f_i^a f_i^b = -\eta_{ij}$.
 - Let P be the space of all observer frames.
 - Natural projection $\pi: P \to O$ discards spatial frame components.

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$$O=\bigcup_{x\in M}S_x.$$

- Tangent vectors $y \in S_x$ satisfy $g_{ab}^F(x, y)y^ay^b = 1$.
- Construct orthonormal observer frames:
 - \Rightarrow Complete $y = f_0$ to a frame f_i with $g_{ab}^F(x, y)f_i^a f_j^b = -\eta_{ij}$.
 - Let P be the space of all observer frames.
 - Natural projection $\pi: P \to O$ discards spatial frame components.
- Group action on the frame bundle:
 - SO(3) acts on spatial frame components by rotations.
 - Action is free and transitive on fibers of $\pi: P \to O$.
 - $\Rightarrow \pi: P \rightarrow O$ is principal *K*-bundle.

Outline

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Observers

Metric geometry

Timelike curve γ :

$$\begin{array}{cccc} \gamma & : & \mathbb{R} & \to & \pmb{M} \\ & \tau & \mapsto & \gamma(\tau) \end{array}$$

$$g_{ab}\dot{\gamma}^a\dot{\gamma}^b=-1$$

Orthonormal frame *f*:

$$f_0^a = \dot{\gamma}^a$$

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$$\gamma : \mathbb{R} \to \mathbf{M} \\
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$$\dot{\gamma}(au) \in \mathcal{S}_{\gamma(au)} \subset \mathit{TM}$$

Canonical lift Γ:

$$\Gamma(\tau) = (\gamma(\tau), \dot{\gamma}(\tau))$$

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Observer curve Γ:

$$\Gamma : \mathbb{R} \to O \\
\tau \mapsto \Gamma(\tau)$$

Lift condition:

$$\tilde{\mathbf{e}}^i\dot{\mathbf{\Gamma}}(\tau)=\delta_0^i$$

Orthonormal frame f:

$$f \in \pi^{-1}(\Gamma(\tau)) \subset P$$

Inertial observers

Metric geometry

Minimize arc length integral:

$$\int_{t_1}^{t_2} \sqrt{|g_{ab}(\gamma(t))\dot{\gamma}^a(t)\dot{\gamma}^b(t)|} dt$$

Geodesic equation:

$$\ddot{\gamma}^a + \Gamma^a{}_{bc}\dot{\gamma}^b\dot{\gamma}^c = 0$$

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Geodesic spray:

$$\mathbf{S} = y^a (\partial_a - N^b{}_a \bar{\partial}_b)$$

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$$\dot{\Gamma}(\tau) = \mathbf{S}(\Gamma(\tau))$$

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- Observer trajectories and canonical lifts:
 - Observer trajectory γ in M.
 - Lift γ to a curve $\Gamma = (\gamma, \dot{\gamma})$ in TM.
 - Curves Γ in TM are canonical lifts if and only if

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$$\dot{\Gamma} = \mathbf{S} = y^a \delta_a$$
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- Observer curves:
 - Consider curve Γ in O.
 - → Tangent vector splits into translation and boost:

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- Components are relative to observer's frame.
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- Boost component of the tangent vector:
 - Measures acceleration in observer's frame.
 - Inertial observers are non-accelerating: $b^{\alpha}\dot{\Gamma} = 0$.
 - \Rightarrow Inertial observers follow integral curves of time translation: $\dot{\Gamma} = \underline{e}_0$.

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Einstein-Hilbert action:

$$S_{\text{EH}} = \frac{1}{2\kappa} \int_{M} d^4 x \sqrt{-g} R$$

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Using linear connection:

$$S_{\mathsf{L}} = rac{1}{\kappa} \int_{\Sigma} \mathsf{Vol}_{\tilde{G}} \, g^{F\,ab} R^c_{acb}$$

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$$\mathcal{S}_{\mathsf{H}} = \int_{\mathcal{O}} \tilde{\mathit{b}}^{lpha}([\underline{\tilde{e}}_{lpha},\underline{\tilde{e}}_{0}]) \, \mathsf{Vol}_{\mathcal{O}}$$

Using Cartan curvature:

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Gravity from Cartan to Finsler

MacDowell-Mansouri gravity on observer space: [S. Gielen, D. Wise '12]

$$\mathcal{S}_{G} = \int_{O} \epsilon_{lphaeta\gamma} \operatorname{tr}_{\mathfrak{h}}(F_{\mathfrak{h}} \wedge \star F_{\mathfrak{h}}) \wedge b^{lpha} \wedge b^{eta} \wedge b^{\gamma}$$

- Hodge operator ★ on ħ.
- Non-degenerate H-invariant inner product tr_h on h.
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- Hodge operator ★ on ħ.
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- Boost part $b \in \Omega_1(P, \mathfrak{y})$ of the Cartan connection.
- Translate terms into Finsler language (with $R = d\omega + \frac{1}{2}[\omega, \omega]$):
 - Curvature scalar:

$$[e,e] \wedge \star R \leadsto g^{F\,ab} R^c_{\ acb} \, dV$$
.

Cosmological constant:

$$[e,e] \wedge \star [e,e] \leadsto dV$$
.

Gauss-Bonnet term:

$$R \wedge \star R \leadsto \epsilon^{abcd} \epsilon^{efgh} R_{abef} R_{cdgh} dV$$
.

⇒ Gravity theory on Finsler spacetime.

Gravity from Finsler to Cartan

• Finsler gravity action: [C. Pfeifer, M. Wohlfarth '11]

$$S_G = \int_O d^4x \, d^3y \, \sqrt{-\tilde{G}} R^a{}_{ab} y^b \, .$$

- Sasaki metric G
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$$\begin{split} \textit{d}^{4}\textit{x}\; \textit{d}^{3}\textit{y}\; \sqrt{-\tilde{\textit{G}}} &= \epsilon_{\textit{ijkl}}\epsilon_{\alpha\beta\gamma}\, \textit{e}^{\textit{i}} \wedge \textit{e}^{\textit{j}} \wedge \textit{e}^{\textit{k}} \wedge \textit{e}^{\textit{l}} \wedge \textit{b}^{\alpha} \wedge \textit{b}^{\beta} \wedge \textit{b}^{\gamma}\,, \\ \textit{R}^{\textit{a}}{}_{\textit{ab}}\textit{y}^{\textit{b}} &= \textit{b}^{\alpha}[\underline{\textit{A}}(\mathcal{Z}_{\alpha}),\underline{\textit{A}}(\mathcal{Z}_{0})]\,. \end{split}$$

⇒ Gravity theory on observer space.

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Summary

- Finsler spacetimes
 - Generalization of metric spacetimes.
 - Geometry defined by function *L* on *TM*.
 - Lengths measured by Finsler function $F = |L|^{\frac{1}{n}}$.
 - Metric generalized by Finsler metric g_{ab}^F .

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- Different geometries provide compatible definitions of:
 - Causality
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 - Observables
 - Gravity

Open questions

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